

ErmaFlex #7

# Clustering Cashing

System for grouping jars and bottles in cartons

## Clustering at a glance

- Highlights & Key Activities
  - Assembly, disassembly, reconditioning and adjustments of gripper heads
  - Position control
  - Change of format: pots, bottles, cartons for pots and cartons for bottles
- > Specific components
  - 2-axis transfer system consisting of a DC electric motor, a pneumatic cylinder and an incremental encoder
  - Control cabinet with PLC, dialogue terminal and variable speed drive for control
  - Two gripping heads with grippers and suction cups

This system is accompanied by a technical and educational file

### References

- RE50-RE51: Basic grouping frame without gripper head and with control cabinet equipped with a Schneider M340 PLC and a Siemens TP177 colour touch panel
- RE52: Suction cup gripping head for pots (For RE50-RE51)
- RE53: Gripper head for vials (For RE50-RE51)
- RE54: RFID Tracking and Logistics Option for Regrouping Collection
- ✓ UC13: Supervision Option
- UC90: Option: Fault box for electrical cabinet, remotely configurable on a tablet (Not supplied)
- IO00: IO-Link package for electrical and pneumatic measurements
- SK20: Sick TDCE Smart IoT Gateway Kit & Smart Sensors for Ermaflex Clustering
- UC51: Option: Visual Instructions & Monitoring of Production Indicators on the Tulip open application environment and touch pad, for one machine
- UC52: Option Visual instructions on Tulip open application environment and touch pad, for one machine
- ✓ AE30: Schneider M340 PLC / Web Server with UnityPro license
- MN13: Programmable 3D digital mock-up Grouping:/Cashing

## Bac PRO PLP - MSPC BTS MS - IUT Universities - Engineering schools

IoT Sick Pack 🛛 🟵 IO-Link 🔶 TULIP



- ✓ L/ W/ H: 3000 x 2200 x 2250 mm
- ✓ Electrical energy: 400V three-phase + neutral
- ✓ Pneumatic energy: 7 bar
  - Weight: 550kg

# **Functional architecture**

#### Functional description

The grouping and packing module is designed to group different types of products and arrange them in cartons or trays.

## Sub-assembly Product Conveyance

- ✓ It allows the transfer of products from the entrance of the system (packaging unit) to the grouping area.
- ✓ It is mainly made up of:
- ✓ A pallet chain conveyor
- ✓ A three-phase asynchronous electric motor to drive the vanes
- Two proximity sensors (fibre optics) to detect the presence of products on the conveyor and to create a buffer stock

## Sub-assembly Conveying of cartons

- ✓ It allows the transfer of cartons from the system entrance to the case packing area.
- ✓ It is mainly made up of:
- · A conveyor belt
- A three-phase asynchronous electric motor to drive the belt
- Two photoelectric cells to detect the presence of cartons respectively under the gripping head and at the exit or vision lock
- A box indexing device associated with a cylinder
- A box blocking device associated with a jack
- A device for indexing the boxes at the exit lock associated with a cylinder



## Functional architecture (continued).



- Two magnetic limit switches (ILS) B14 and B15, mounted on the 3A1 cylinder

More information on www.erm-automatismes.com

Visualisation

Marche Arrêt

0.30 m/s



# Educational activities Pedagogical approach.

- Functional analysis
  Study of technologies: electrical, pneumatic, and mechanical
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- Programming
- Position control
  Change of formatic
- Change of format :
  - 2 gripping heads: with grippers for bottles, and with suction cups for jars
  - 2 types of cartons or trays (for pots or bottles)
- Assembly/disassembly and repackaging
- ✓ Settings
- ✓ Steering

### TP1: Changing the format of the Regrouping unit Cashing

- Timeline of the TP:
  - Learn about the format change, prepare your tools and your workstation
  - Making the automated mechanical system safe
  - Replace sub-assemblies Gripper and Funnel Guide
  - Adjust the Product Conveyor, Funnel Guide and Case Conveyor sub-assemblies.
  - Carry out tests and final adjustments

# TP2: Designing a diagnostic process (Failure of the "Gripper down" acquisition chain)

- Timeline of the TP:
  - Identify the failure
  - Locate the fault
  - Formulating hypotheses
  - Analyse and rank assumptions by probability of occurrence and ease
    of verification
  - Carry out checks, tests and trials
  - Diagnose

#### TP3: Designing a diagnostic process (Safety loop failure)

- Timeline of the TP:
  - Identify the failure
  - Locate the fault
  - Formulating hypotheses
  - Analyse and rank assumptions by probability of occurrence and ease of verification
  - Carry out checks, tests and trials
  - Diagnose



Clamping unit integrated in the Ermaflex line

# **RELATED & COMPLEMENTARY PRODUCTS**

#### PLC & Touch Panel + Digital Twin in VU Pro





Programming in Schneider and Siemens environments and then simulation in the digital twin

## More information on www.erm-automatismes.com



# ASSOCIATED & SUPPLEMENTARY PRODUCTS (continued)

