

Ermalean

Didactic assembly line for learning Lean Six Sigma and digital technologies of Industry 4.0





ErmaLean in right configuration, with Omron TM5 Cobot & Vision Station



Shop with Pick To Light



Visual management area

What is Ermalean?

- ◆ **ErmaLean is an evolutionary workshop that** allows learners to be confronted with realistic industrial situations (**assembly of a mechatronic unit**) in order to carry out learning activities on the **application of continuous improvement tools** and methodologies as practised in an industrial environment
- ◆ The learning process alternates between production phases and periods of performance analysis, which are sources of analysis with Lean and Six Sigma tools. The application of these changes enables the objectives expected by the client to be achieved in terms of quality, cost and lead time.
- ◆ The deployment of ErmaLean requires a minimum workshop area of 100 m² for the different set-up configurations required for the activities.

Strengths:

- ◆ **A management position with:**
 - **Supervision PC** with Wi-Fi link
 - **Whiteboard** and communication materials
- ◆ **Five assembly stations that can be adjusted according to the performance being tested:**
 - **elements of management and evolutionary steering,**
 - assembly stations allow for **several set-ups** (independent, in-line, U-shaped),
 - **RFID tracking on assembly pallets and transfer between stations.**
- ◆ **Dynamic storage system designed for all the containers** required for three product variants
- ◆ **Handling, component supply and inter-station transfers** are designed for the volumes of WIP encountered at the various locations tested with scalable performance levels for the entire process
- ◆ **Integrated assembly tools and control means**, some of which are linked to the supervision system (measurement of screwing torques, **dimensions, conformity tests, etc.**)
- ◆ **The evolution towards the assembly of other products is possible** by the simple adaptation of the pucks and the evolution of the various documentations.

Associated systems:

- ◆ **ON00:** Omron TM5 Cobot & Vision Station: Omron TM5 4kg R900 collaborative robot with on-board camera, on a mobile chassis with height adjustment and work surface
- ◆ **ON17:** OnRobot RG2 Collaborative Electric Clamp Option for OMRON Cobot Station
- ◆ **AG00:** AGV MiR100 ErmaSmart
- ◆ **AG10:** AGV + Cobot " Mir100 + UR5 eSeries " Ermasmart
- ◆ **UR17:** OnRobot RG2 Collaborative Electric Clamp option for Cobot UR

References & Options:

- ◆ **LN10:** ErmaLean, Didactic assembly line for Lean 6 Sigma training
- ◆ **Option LN11:** Added value for a height adjustable workstation
- ◆ **Option EA02:** Sensopart Industrial Vision Case (For parts presence control)
- ◆ **Option LN13:** Torque control screwdriver connected to Tulip, with suction system for gripping and "head up" screw dispenser

Educational activities:

- ◆ Different production sequences with evolving performances
- ◆ Progressive use of analysis tools leading to the evolution of workstations and procedures to reach the final objective of the customer order rate: the TAKT TIME
- ◆ Ranges of assemblies for different performance levels
- ◆ Lean and 6 Sigma TP with Excel file for each tool, which can be modified, provided with the course:
 - a tab for each document frame to be used in support of the exercise
 - a instructions tab explaining the chronology of the practical work where the uses of the documents and materials are detailed
- ◆ The computer application allows the display (ranges, instructions, etc.) and feedback (time, measurements, defects, etc.) of each station. This data is used for analysis and research into improvement solutions.
- ◆ Creation and improvement of ranges in the Manufacturing Assistance software "Tulip"

- Practical application of the main tools used in Lean 6 Sigma (VSM, Kanban, Capability, Variability...)

Conducting projects according to the DMAIC chronology: Implementation of process improvement project management tools and other teamwork tools

- Lead time: Highlighting the impact of balancing items

- Takt Time: Measurement, analysis and evolution of the flows used: Material (batches, part to part) People (implementation) and Information

- Kaizen: Implementation of Kaizen tools (5S, TPM...)

- Quality: Application of Six Sigma tools (Capability; Regression; R&R; ...)

- Workshop management: Consideration of the different parameters of business management

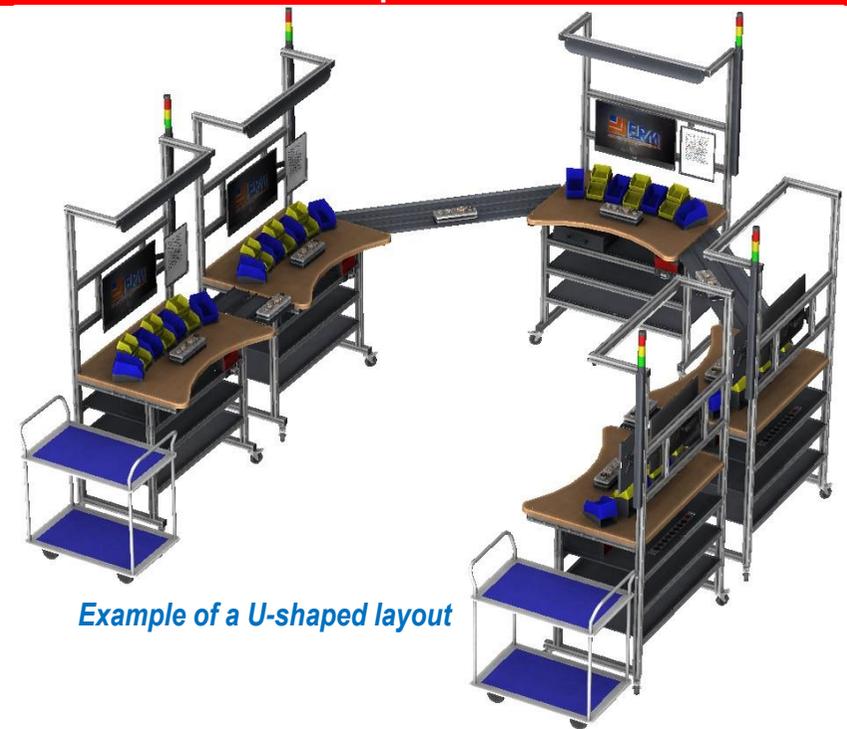
- Ergonomics & Safety: Impacts of ergonomic and working conditions in safety standards

Basic configuration:

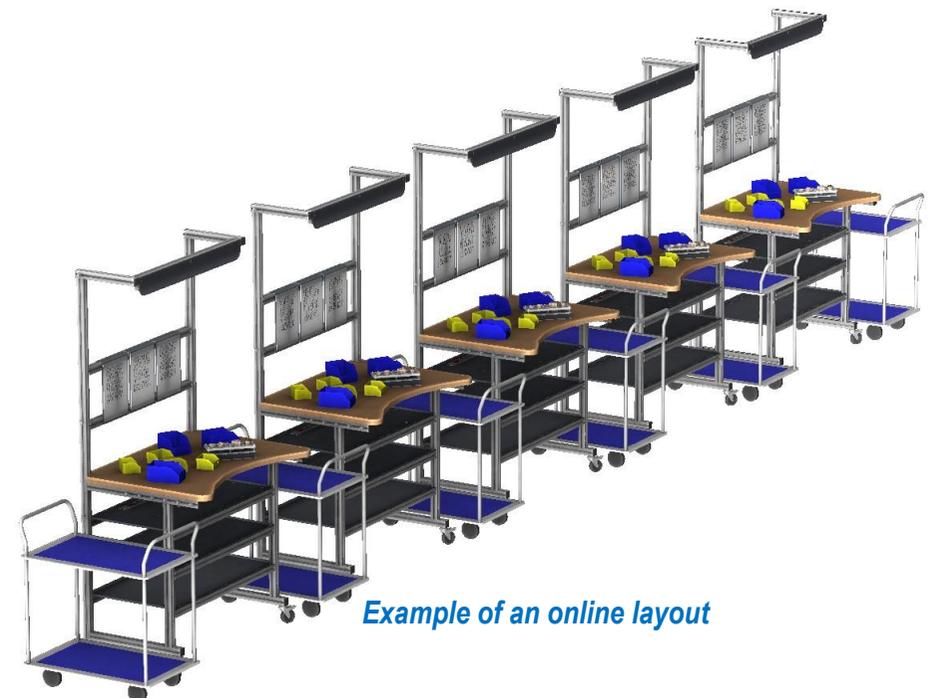
The basic configuration comprises the means necessary to assemble a product in different configurations:

- Planetary gear motors (3 product configurations available)

It is also compatible for the integration of other products to be manufactured. Indeed, the evolution of the line towards other products has been integrated from its conception. This is facilitated by a minimum of specific tooling, a totally open software suite and a very intuitive development environment.



Example of a U-shaped layout



Example of an online layout

Planetary gear motor :

The selected model is a planetary gear motor consisting of :

- ◆ 1x DC motor 2,5W 1,3 - 3Vdc - 6250 to 12200 rpm - Shaft diameter 2mm
- ◆ 1x Engine shell
- ◆ 1x Motor mount
- ◆ 1x Sun gear (gearbox body)
- ◆ 1x Inner sun gear
- ◆ 4x Satellite
- ◆ 1x Satellite holder
- ◆ 3x M3x25 mm screws
- ◆ 3x CHC screw M3x8mm
- ◆ 3x FHC screw M3x8mm
- ◆ 3x FHC screw M3x12mm
- ◆ 8x M3 nut
- ◆ 5x Flat washers narrow M3
- ◆ 5x Ball bearings Dint3 Dext8 e4

This package may be subject to change.

This product has a high degree of variability:

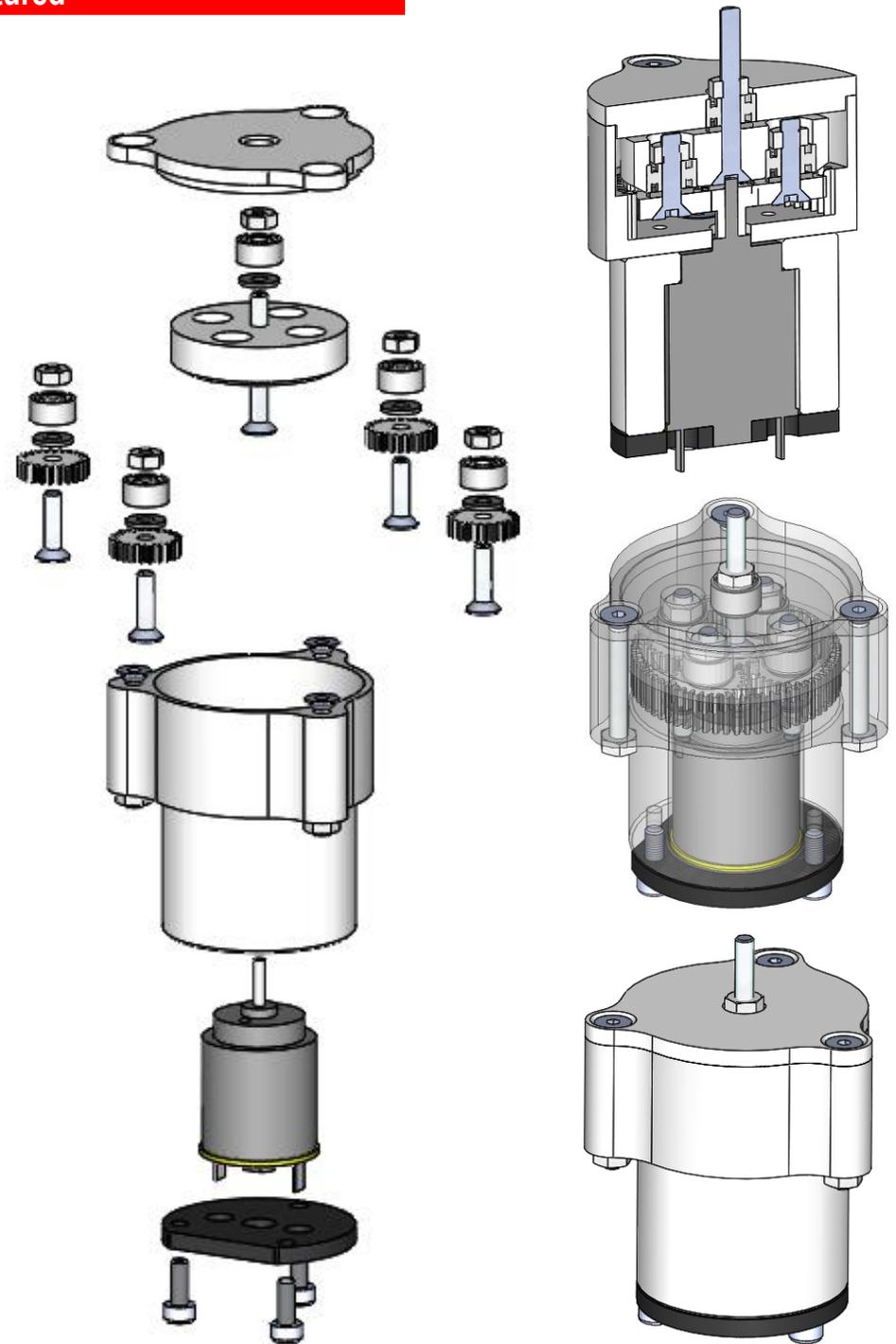
- ◆ Reduction ratio
- ◆ Housing colour
- ◆ Shaft diameter...

We supply three different models as part of the initial delivery.

The following quality controls can be performed:

- ◆ Dimensions (Shaft diameter - Housing thickness...) with caliper connected
- ◆ Good mechanical and electrical operation with power supply connected (voltage sent to the motor, current absorbed, speed of rotation)
- ◆ Presence of parts during assembly, with connected camera (Option)

Upgrading to other products (e.g. shifters or customer-defined products) is facilitated by a minimum of specific tooling, a fully open software suite and a very intuitive development environment.



Five modular assembly stations with :

- ◆ **Materialization** => Aluminium profile frame with adjustable work surface
- ◆ **Ergonomics** => Set of 5 ergonomic chairs; workstation layout + Height adjustment of worktops (Option LN11)
- ◆ **Adaptability to physical flows** => Storage racks and workstation organisation accessories, including removable container supports for ergonomic box positioning
- ◆ **Management / Steering** => Paper document holder (removable)
- ◆ Signalling => Andon 3-colour controllable beacon (removable)
- ◆ Tool drawer => Tool kit for product assembly
- ◆ Traceability => RFID reader connected, 1 waste counting sensor
- ◆ Connected control => Tulip IoT gateway and IO-Link master
- ◆ Management/Digital control => Touch computer (removable)
- ◆ **MES and Manufacturing Assistance software** => Tulip giving access to digital procedures on each workstation and feedback from each workstation



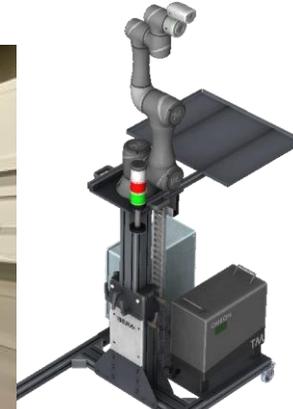
Tools for workstations & control integrated and partly linked to supervision :

- ◆ **Traditional assembly** => hex keys, screwdrivers, flat keys, plotters, magnets
- ◆ **Manual measurement** => 5 Stopwatches and 2 hand counters with ring
- ◆ Product performance control under different controlled voltages=> Tachometer
- ◆ **Dimensional control connected** => Caliper connected
- ◆ **Electrical measurements connected** => Power supply controlled and connected
- ◆ **Connected assembly** => Connected screwdriver with torque control (Option LN13)
- ◆ **Productivity improvement** => Vacuum system for screw gripping + Head up screw dispenser (Option LN13)
- ◆ **Vision control** => Camera connected to Tulip (Option LN12)

Measurements of torque, dimensions, presence of components, electrical resistance, voltage, current, temperature, humidity, time, and operation of the assembly are connected to the Tulip supervision and can be fed back into NODERED for possible exploitation by other software.

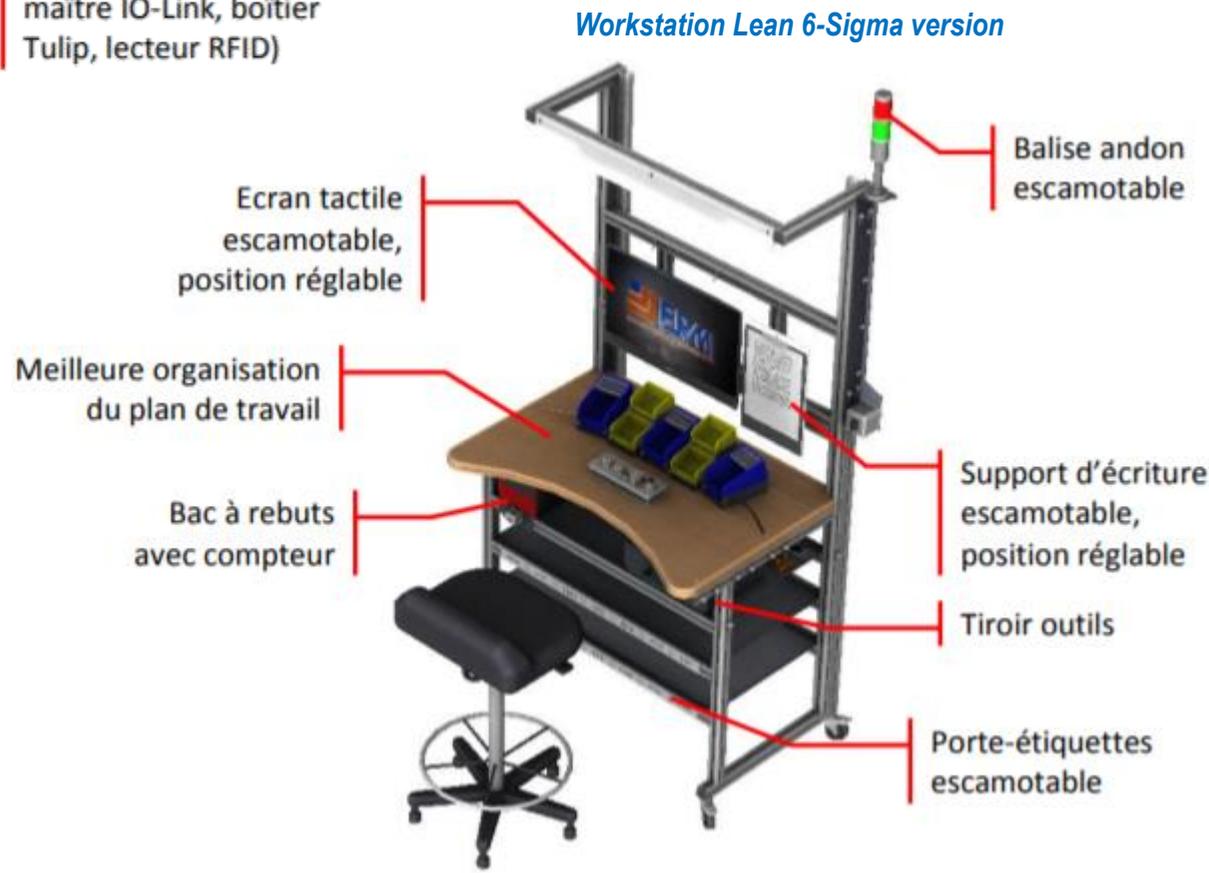
Omron TM Cobot & Vision Station (Option ON00):

- ◆ **Materialization** => Robot support frame with height adjustable position
- ◆ **Collaborative robot** => OMRON TM5-900, range 900mm, payload 4kg, with on-board camera
- ◆ **Safety/collaboration** => 2 laser scanners for the management of collaborative working areas (speed reduction/stop depending on the distance from the operator) and automatic work resumption (Option)
- ◆ **Handling** => OnRobot collaborative electric gripper (Option)
- ◆ **Software** => Graphical cobot programming environment
- ◆ **Programming** => Programming of control and assembly tasks in collaborative and autonomous mode



**Omron TM Cobot & Vision Station
in packaging operation at the end
of assembly**

Production line equipment and logistics



Basic and LEAN warehouse (Included in LN10):

- ◆ **Storage** => Allows the storage of assembly parts
- ◆ **Material:** Aluminium profile frame and gravity racks
- ◆ **Management /Steering** => Document support
- ◆ **Management/Digital control** => Touch computer
- ◆ **Manufacturing Assistance*** => Tulip **software** to assist the order picker in the tasks he has to perform
- ◆ **Connected control** => Tulip IoT Gateway, Pick to light, Bar code scanner and QR code
- ◆ **Product identification** => Coding and QR Code
- ◆ **Storage** => Set of containers required for three product variants and sized to support 3-hour production TPs.
- ◆ **Distribution and flow management** => Carried out by manual trolleys



Flow management / Workshop configuration :

- ◆ **Supply of spare parts to the stations:** 1 Trolley with 3 trays
- ◆ **Station/station flow:** 4 Trolleys with 2 trays
- ◆ **Manual conveyors** => 4 straight inter-station conveyors for 1 to 3 product lines, 2 90° inter-station conveyors for 1 to 3 product lines



Specific products/means :

- ◆ 10 Basic pucks
- ◆ 30 pucks adapted to the product
- ◆ 100 RFID chips for pallets and boxes
- ◆ Bolt kit for assembly of 60 geared motors
- ◆ Spare parts kit for the assembly of 20 geared motors in configuration 1
- ◆ Spare parts kit for the assembly of 20 geared motors in configuration 2
- ◆ Spare parts kit for the assembly of 20 geared motors in 3-way configuration
- ◆ Batch of 0.3L and 1L storage bins, in sufficient quantity to ensure the production of products in the 3 configurations
- ◆ Batch of bins for the disposal of finished products
- ◆ Adhesive tape for road marking



AGV MiR100 (Option AG00) :

- ♦ **A Mir100 mobile robot** (Manufacturer: Mobile Industrial Robots - Origin: Denmark) with an autonomy of 10 hours or 20 Km
- ♦ **A wired charger** (100-230Vac 50/60HZ to 24V max 15A)
- ♦ **An Intel® RealSense™ 3D camera** for obstacle detection.
- ♦ **A shelf frame** 760x440x700mm with a support for a shelf
- ♦ **Two shelves** 700x440x30mm
- ♦ **A tablet** constituting the human-machine interface (HMI)



AGV + Cobot "Mir100 + UR5 eSeries" (Option AG10) :

- ♦ **A Universal Robots UR5 eSeries collaborative robot**
- ♦ **A collaborative gripper** for handling the objects in question (Option UR17)
- ♦ **A 450x420x10mm tray** for the placement of handled objects (boxes, trays...)
- ♦ **A Mir100 mobile robot** with 10 hours or 20 km autonomy
- ♦ **A wired charger** (100-230Vac 50/60HZ to 24V max 15A)
- ♦ **A second Li-NMC battery**, 24 V, 40 Ah
- ♦ **An Intel® RealSense™ 3D camera** for obstacle detection.



Computer hardware and applications

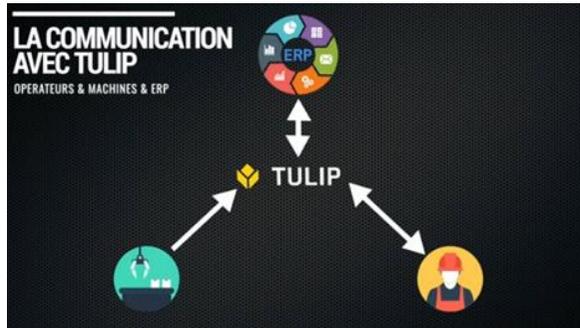
All PCs, monitors and connected tools in the installation are networked through the 4G wifi router provided. Station status and other information is stored in the TULIP cloud and can be accessed on any PC in the line and any other PC you may wish to connect to through your TULIP session.

Each pallet used as an assembly support and transfer of sub-assemblies between stations is equipped with an RFID memory chip and each assembly station has an RFID reader, this equipment allows the tracking of each movement produced by sending information to the database of the supervision PC (Tulip).

For each station, a display dedicated to the function of the station is controlled by the Tulip software.

Presentation of Tulip software (Manufacturing Assistance & MES)

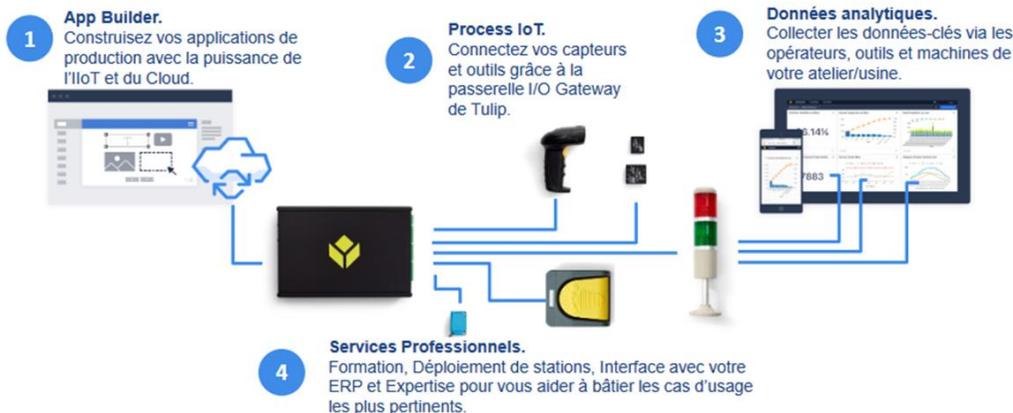
Tulip is a software solution for the digitalisation of production lines and rapid deployment of MES functions.



Tulip is developed in Boston (USA) and used by hundreds of companies in the world to assist production operators and monitor workshops.

Use cases

- ◆ **Visual work instructions:** Guide operators through visual procedures instead of those on paper.
- ◆ **Training:** Simplify and continuously improve training procedures.
- ◆ **Audit & Quality:** Replace paper forms by applications with IoT tools (cameras, scales, ...)
- ◆ **Machine Monitoring and Maintenance:** Real-time acquisition of machine data during production
- ◆ **Task tracking and visibility:** Import OFs from an ERP (Odoo, etc.), program production indicators (TRS, MTBF, productivity rate, etc.) and display them on dashboards
- ◆ **Digital Lean:** Deploying Digital Lean tools and dashboards



The main functions in production management and maintenance

- ◆ Creation of digital work procedures
- ◆ Monitoring of machine data
- ◆ Communication with an ERP (Enterprise Resource Planning)
- ◆ Calculation and display of performance indicators (TRS, MTBF, etc.)
- ◆ Digitalisation of quality forms
- ◆ Digitalisation of audit forms



Tulip's strengths:

- ◆ **Disposal of all paper documents**
- ◆ **Easy and quick programming** of applications and very simple handling
- ◆ **Possibility** to make **mathematical calculations** for the determination of **production indicators**
- ◆ Visualisation of all production-related information on a tablet or computer
- ◆ Customisation of dashboards: by machine or by production line or by product
- ◆ Communication with remote machines through the Kepware communication server and the NODERED platform
- ◆ Possibility of using devices connected to the workstations (scales, calipers, cameras, etc.)
- ◆ The Tulip software user manual will be provided.

Presentation of Tulip software (Manufacturing Assistance & MES)

Tulip screen views for push manufacturing (PO: Production Orders)

TULIP LN10-Gamme A

ID	Date planifiée	Quantité
P005	2022-02-09 14:00:00 +01:00	10
Quantité produite	Numero Run	
0	RUN36	
Gamme Produit	Type motoreducteur	Description
A	M197	Production des motoreducteurs M197
Statut	OT1	OT2
planifié	planifié	planifié
OT3	OT4	OT5
planifié	planifié	planifié

Palet en cours N° : 7

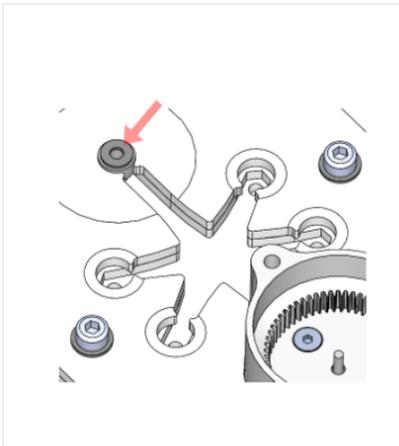
La quantité à produire est : 10pièces

⌵ MENU ⏪ ⏩

OF screen Production order

TULIP LN10-Gamme A

Poste N° : Poste 3 Ordre de fabrication : P005 Référence : M197 Temps : 0:07



Opération 50
Poser et aligner une rondelle sur le roulement.

Composants
- MXEV6

Palet en cours N° : 7

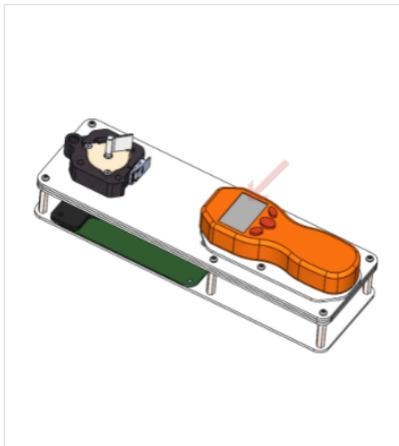
⌵ MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut ⏪ Précédent Suivant ⏩

Assembly Step screen

Screen Control step connected (Tachymetry)

TULIP LN10-Gamme A

Poste N° : Poste 1 Ordre de fabrication : P005 Référence : M197 Temps : 0:11



Opération 40
Déposer le motoreducteur du palet et réaliser un test de fonctionnement

Tensions et courants :
Tensions et courants (1,5V) : Tension Courant

Tensions et courants (3V) : Tension Courant

Palet en cours N° : 7

⌵ MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut ⏪ Précédent Suivant ⏩

Tulip screenshots for lean manufacturing

TULIP LN10-Gamme B 0:05

Poste N° : Poste 1 Palet N° : 23 Référence : M 213 Temps : 0:05

Opération 20
Positionner un palet vide sur le plan de travail

Attente positionnement palet sur le plan de travail

Composants

- Un palet vide
- MBII1
- MXEP1
- MXEV2
- MXII4

M 197 M 213 M 218

MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut

Screen Initial step

Connected control stage screen (Dimensions)

TULIP LN10-Gamme B

Poste N° : Poste 1 Palet N° : 23 Référence : M 213 Temps : 0:07

Opération 60
Extraire motoréducteur du palet, avec pied à coulisse mesurer la hauteur de l'ensemble et valider

Mesure Pied à coulisse : 18.2 mm
Min : 15 mm Max : 30 mm

Produit conforme

M 197 M 213 M 218

MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut

Screen Control step connected

TULIP LN10-Gamme B 0:09

Poste N° : Poste 1 Palet N° : 23 Référence : M 213 Temps : 0:09

Opération 70
Mise en place des 3 vis et serrage

Composants

- MXEV1

Outils
Clé Allen 2.5mm

M 197 M 213 M 218

MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut Précédent Suivant

Assembly Step screen

Connected control stage screen (Tachymetry)

TULIP LN10-Gamme B

Poste N° : Poste 1 Palet N° : 23 Référence : M 213 Temps : 0:14

Opération 80
Réaliser l'opération de contrôle conformité et performance

Test 1.5V Arrêter test 1.5V

Tension Alimentation :

Mesure Tachymétrique 1 : 1120 tr/min
Min 1 : 1000 tr/min Max 1 : 2000 tr/min

Résultats des mesures
Tensions et courants (1.5V)
Tension 1,3V Courant 1,288A

M 197 M 213 M 218

MENU Etat normal Besoin d'aide Etat bloquant Déclarer rebut Précédent Suivant

Education through action

Using ErmaLean, students will seek efficient organisation through performance measurements of their work, seek and implement improvement solutions and use Industrial Transformation 4.0 technologies and tools.

A red thread for the animation is available for the trainer, which allows him to have a chronology of the animations and with configuration of the material,

Each production period lasts about 2 hours, followed by a **feedback synthesis**, **deviations from the initial objective are** qualified, a period of **analysis and search for solutions** is initiated in the form of a project using **Lean Six Sigma tools**.

The solutions are implemented and followed by a **new production period**.

This exercise can be repeated up to four times depending on the level of learning to be achieved in the students' programme,

The functions to be performed are assigned and an explanation of the role of each is given to each student.

The different functions are: Customer; Manager; Operator; Logistician; Observers,

Depending on the number of learners in the group, some or all of the functions will be assigned

Different types of flows are foreseen (Push; Pull; Kanban; Product Standardisation), they allow different and evolving levels of performance.

Through the different scenarios, they will be able to :

- Implement industrial developments and innovations as part of **continuous improvement**, in line with the organisation's strategy and digital developments
- **Leading a 4.0 optimisation project** for all stages of the value chain, all stages of the product life cycle
- **Measuring and analysing the performance** of a process/machine/workshop delivering a product or service
- Define the priority areas of progress that contribute to the objectives of Enterprise 4.0
- Supporting the improvement of company performance by putting **into practice and transferring tools focused on and around people**
- Monitor the results of **flow management**, improve the organisation and operation of flow management
- Implementing **knowledge** and skills **management** in a 4.0 environment
- Integrating **occupational health as a strategic lever for the** performance of companies of the future
- Apply **methods of communication and project management** aimed at excellence

Pedagogical proposal

The elements proposed are the bases of practical work with scenario and documentary supports for their development, they are of different levels to meet the different degrees of training to be provided. All the documents are written in French and given in digital format (modifiable).

Adaptation and design of the workshop :

Assembly range :

Several assembly ranges for the three configurations of geared motors on 5 stations are provided, which allow the use of the line to be initiated. The various practical exercises allow the line to be upgraded.

Coding of components :

A codification is prepared for each component.

Identification :

Labels (in a format suitable for the place of use) for the boxes, the in- and outfeed radii of the dynamic storage system, the in- and outfeed for the supply area of each station, and for the trolleys of the milkman's round are provided.

Organisation of the dynamic storage unit

Component box layout plans for each front (inlet and outlet) are provided.

On the input and output side, a "Pick to Light" facility is managed by scanning the QR code included on the label of each component box, this configuration, used at an advanced stage of development (TP related to supply time). A stock management system is updated at each movement of components in or out.

For each of these subjects, paper documents are provided and an Excel file is provided to allow for any necessary modifications to be made as a result of developments in the practical exercises.

Structure of the TP materials:

A digital file is provided with all the documents used for the practical exercises.

For each practical course, an Excel file is provided with a tab for each document frame, an instructions tab detailing the uses of the documents and a scenario explaining the timeline of the course. The timeline includes the hardware configurations to be implemented to start the tutorial and a possible final configuration.

All of these files are 'open' and can therefore be modified by users.

Scalability of the system

The proposed workshop is fully modular and will be upgraded from 3.0 to 4.0 mode by adding removable elements as the pedagogy evolves.

In its initial configuration (3.0)

The workshop will operate in offline mode but with the production tools in non-digital format on the workstations and on the "factory cockpit".

Traditional" tools (chronometer, calliper, etc.) will be used to measure the different stages of production.

A dedicated supermarket/manual shop is planned.

In the advanced configuration (4.0)

The workstations and tools will be connected, and the flow of information up and down will be digitised using connected tools and touch screens at each workstation.

In this configuration, a collaborative robot could be equipped with the final station in order to perform assistance tasks (in collaboration)

The production control and line monitoring station will be digitalised thanks to Tulip and will display, in real time, the information deemed key by the production team.

The entire process is designed for the serial assembly of small components.

The evolution towards the assembly of other products of your choice is possible by the simple adaptation of the poses and evolution of the various documentations.

It will also be facilitated by a minimum of specific tooling, a totally open software suite and a very intuitive development environment (Tulip).

The Tulip computer application allows the display (ranges, instructions, etc.) and feedback (measurements, defects, etc.) of each station according to the performance level used. All the scenarios and displays provided can be modified and reconfigured by the users as the Tulip software is totally open and intuitive. At the end of the training, you will be able to create new scenarios and integrate new ranges and products.

Examples of practical work on production organisation

Lead Time

Scenario A/ Inputs :

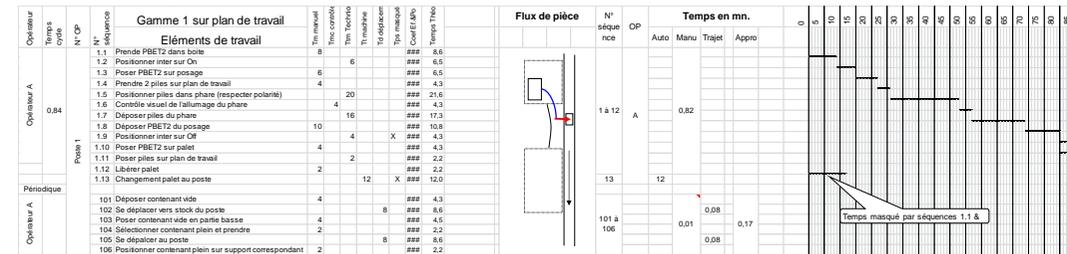
The line is put into production with the original range and the times at each station are timed.

Teaching aim: To highlight the impact of balancing items.

Document generation :

In a computer file in Excel® a "Standard procedure and time" file:

Example:



Range with, for each workstation, the breakdown of times by category and a diagram of movements on the workstation, then a time simulation graph (highlighting imbalances and NVA).

Output: This tool is filled in on the basis of the measurements made, then analysed and modified for a new production period following the improvements found.

Scenario B/ Inputs :

The line is put into production with the original routing and the output timing of the products is recorded.

Teaching aim: To highlight the impact of the type of flow used. (Pushed / pulled).

Document generation :

In a computer file in Excel® a "Requirements Cadence" file:

The rates of change of the requested references are accelerating, the analysis of the lead time shows a lack of reactivity.

Output: One solution is to use the 3 pucks conveyor (1 per reference) in parallel between each station to match the takt time with mixed references.

Other common Lean 6 Sigma tools

Document generation :

In Excel®, one file per tool requiring support and with at least one scenario for implementation in the workshop. For example, the following are covered: Purchase order; Production order; VSM; KANBAN; VARIABILITY on product, on time...

Kaizen

Educational objectives :

Practical application of Kaizen and other teamwork tools.

Document generation :

In Excel® one file per tool requiring supports:

- 5 Why : A framework for conducting problem solving

ERM				Analyse des 5 Pourquoi - Résolution Rapide de Problème				??????															
Sujet: SECURITE <input type="checkbox"/>				QUALITE <input type="checkbox"/>				APPRO <input type="checkbox"/>				LIVRAISON <input type="checkbox"/>				COUT <input type="checkbox"/>				AUTRE <input type="checkbox"/>			
Nom/Prénom				Date				Atelier				Localisation/Processus											
Description détaillée du problème, de la défaillance, détails, données, schéma.												Analyse de la cause première DETECTION "Pourquoi la défaillance n'est pas détectée ?"											
Pourquoi 1:												Pourquoi 2:											
Pourquoi 3:												Pourquoi 4:											
Pourquoi 5:												Actions correctives sur la(es) cause(s) principale(s)											
Occurrence												Responsable				Prévu le:				Réalisé le:			

- 5 S: A site management framework adapted to the line

A monitoring schedule during the construction process and an audit schedule

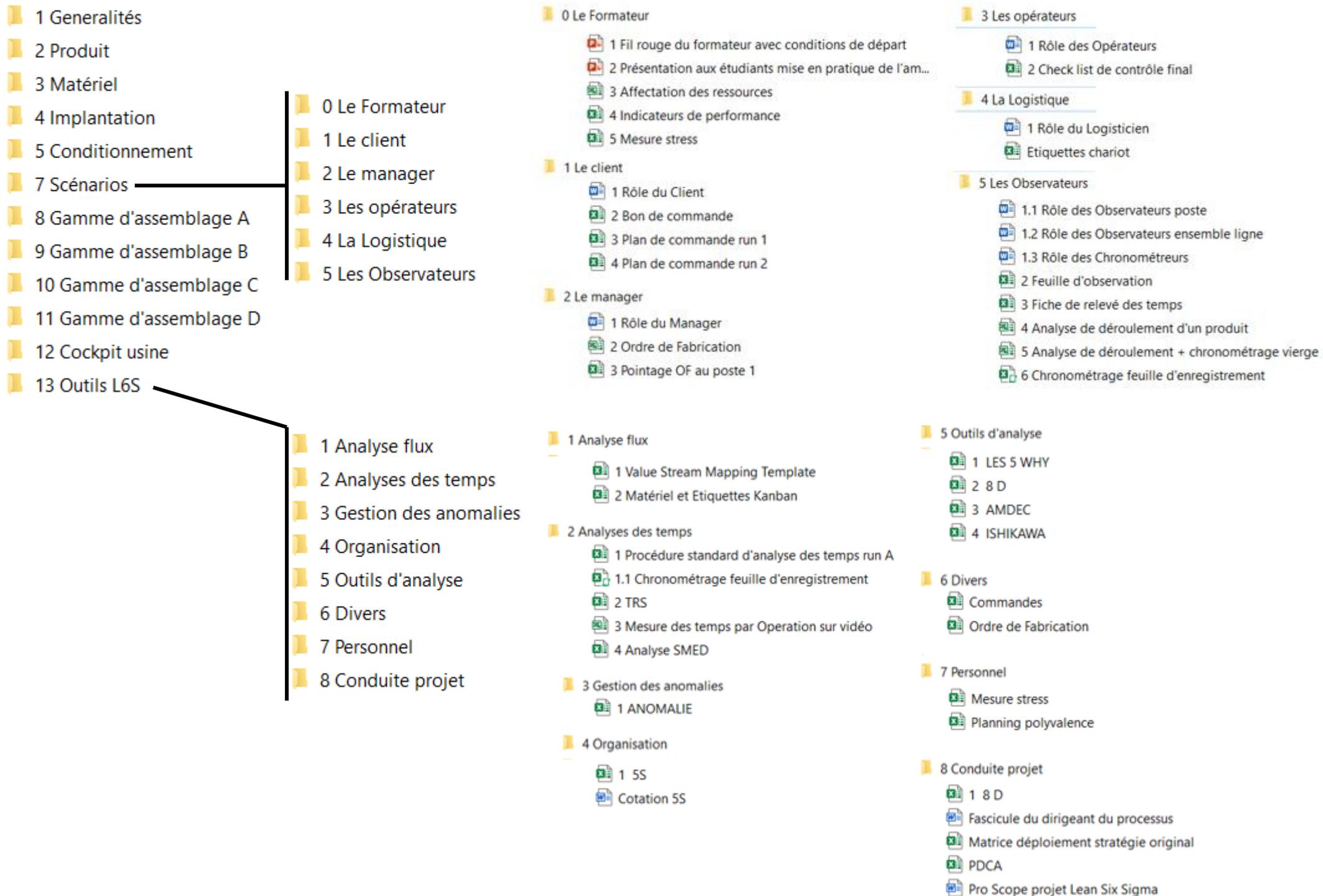
ERM				KAIZEN PLAN D'ACTIONS EN INITIATION CHANTIER 5 S.						
Section: DUT Organisation Industrielle				TP1: 5 S						
Promotion 2009 / 2010										
Découpage de l'atelier en zone d'analyse										
Identifier ce qui peut être ELIMINER										
	P0	P1	P2 & 2.1	P3 & 3.1	P4	P5	P6	Stock I	Stock E	Atelier
Qui										
Quand										
Qté										
Identifier ce qui peut être RANGER										
	P0	P1	P2 & 2.1	P3 & 3.1	P4	P5	P6	Stock I	Stock E	Atelier
Qui										
Quand										
Qté										

- Anomalies: An anomaly declaration form by degree of urgency and a follow-up of processing times.

ERM				T.P.M.				SUIVI DES ANOMALIES							
PERIODE du: 01/02/2009				au: 15/03/2009				Répartition par cause							
Qté en ATTENTE:				Urgence A				Urgence B				Urgence C			
Somme des anomalies:				2				0				0			
Temps moyen de traitement:				0:30				1:00				1:40			
Temps total de traitement:				1:01				1:00				3:20			
Objectifs maxi de durée:				0:15				01:15				03:15			
Temps d'ouverture par jour: 8 Heures															
Codification ANOMALIE:															
	Heure	jour	mois	année	heure	minute	initiales	Cause	Cloture	Temps de traitement en					
									jour	mois	année	heure	minute		
1	A	12	2	9	12	9	J B V	MECANIC	12	2	9	13	0	1	0:51
2	B	12	2	9	13	0	C R	ELECTRI	12	2	9	14	0	2	1:00
3	C	12	2	9	13	0	C F	MECANIC	12	2	9	13	22	3	0:22
4	C	13	2	9	14	2	M P	AUTOMA	13	2	9	17	0	4	2:58
5	A	13	2	9	14	10	L G	AUTOMA	13	2	9	14	20	5	0:10
6	A	13	2	9	15	5	J P B	DIVERS						6	
7	A	13	2	9	16	15	M O P	MECANIC						7	
8														8	
9														9	
10														10	

- Gemba Walk; Suggestion; TPM are prepared with the same flexibility of use with appropriate documents.

(Partial) tree structure of the teaching pack provided



Presentation of the Odoo ERP, CAMM & CMMS (optional)

In the context of projects, ERM has developed a connector between Tulip and the open-source ERP Odoo.

Odoo then acts as a CAPM layer on top of Tulip.

The existence of this Tulip connector ↔ Odoo and our past experience will allow us to achieve this integration, if required, within a limited budget.

The screenshot displays the Odoo ERP interface for the 'Fabrication' (Production) module. The top navigation bar includes 'Opérations', 'Données de base', 'Analyse', and 'Configuration'. The user is logged in as 'Administrator'. The main view is titled 'Articles' and shows a list of 15 products in a grid layout. Each product card includes an icon, a name, a price, and an availability status.

Article	Prix	Disponibilité
Barquette thermoformée rectangle 6 biscuits	0,00 €	0,000 Unité(s)
Barquette thermoformée rond 6 biscuits	0,00 €	0,000 Unité(s)
Biscuit rectangulaire	0,00 €	0,000 Unité(s)
Biscuit rond	1,00 €	0,000 Unité(s)
Boite de 12 biscuits rectangulaires (004)	1,00 €	0,000 Unité(s)
Boite de 12 biscuits ronds (003)	1,00 €	0,000 Unité(s)
Boite de 6 biscuits rectangulaires (002)	1,00 €	0,000 Unité(s)
Boite de 6 biscuits ronds (001)	1,00 €	0,000 Unité(s)
Boite pour barquettes	1,00 €	0,000 Unité(s)
Brut pour usinage fond porte-clé	0,00 €	0,000 Unité(s)
Couvercle de porte-clé	0,00 €	0,000 Unité(s)
Electronique porte-clé	1,00 €	0,000 Unité(s)
Film	1,00 €	0,000 Unité(s)
Fond de porte-clé	0,00 €	0,000 Unité(s)
Porte-clé connecté (Porte clé)	1,00 €	0,000 Unité(s)

The Odoo logo is visible in the bottom right corner of the interface.